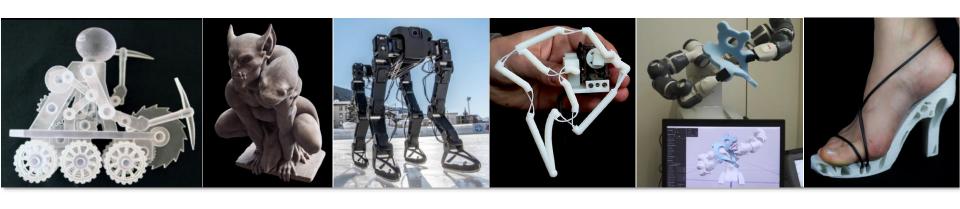
Physics-based Modeling for Computational Fabrication and Robotics



Prof. Dr. Stelian Coros





Course Instructors



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Moritz Geilinger TA





What this course is about...

Physics-based Modeling for Computational Fabrication and Robotics





The context: Industry 4.0

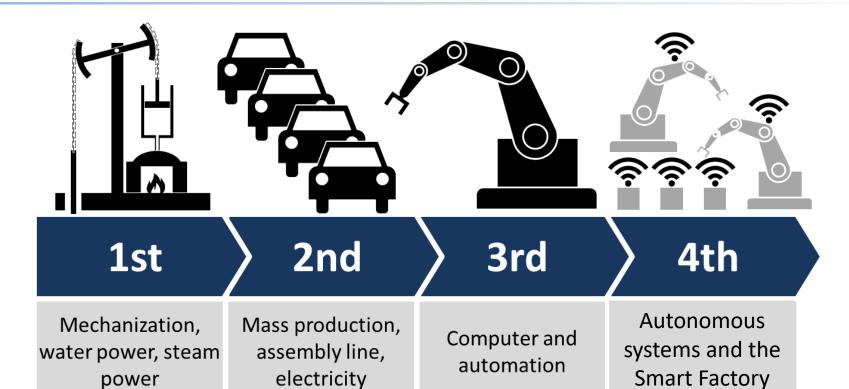




The future of manufacturing is digital!



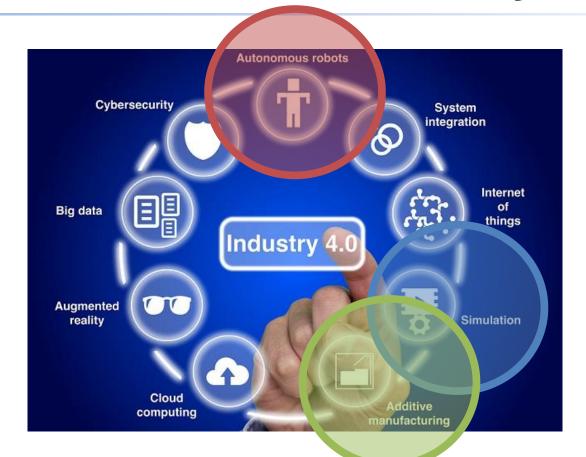
The context: Industry 4.0



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The context: Industry 4.0



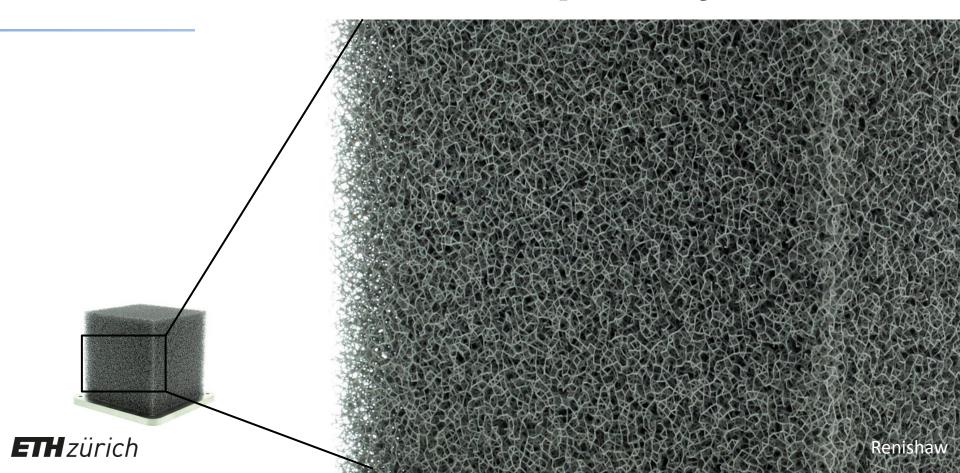




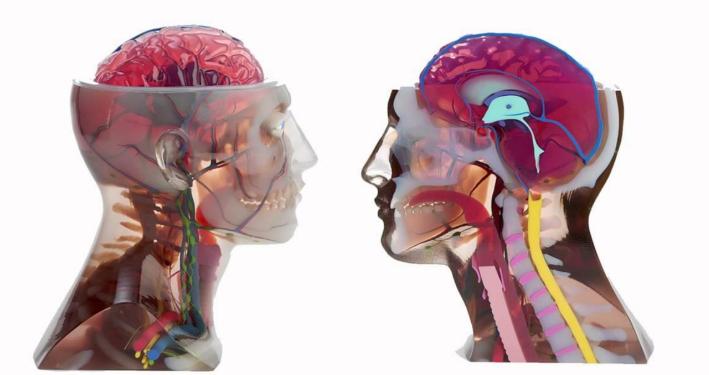
Additive Manufacturing



AM: Geometric complexity



AM: Multi-material capabilities







AM: a shift from mass production to mass personalization





Computational Fabrication

Grand Challenge: mastering the complexity enabled by digital manufacturing

- new opportunities, new challenges
- the gap between "what we can produce" and "what we can design" is rapidly growing
- without new software design solutions, the digitalization of manufacturing cannot go far...





The State of CAD

"Yesterday's software fails today's hardware"

"So far, the brain created the object, and the computer didn't help much."

Carl Bass, former CEO Autodesk

Gian Paolo Bassi, CEO Solidworks







Computational Fabrication

Grand Challenge: mastering the complexity enabled by digital manufacturing

Very much an active research area

 In this course we will see how physics-based simulation models can be used as the foundation for computation-driven design

https://www.manandmachine.co.uk/complex-design-age-additive-manufacturing/



What this course is about...

Physics-based Modeling for Computational Fabrication and Robotics





AM presents fascinating opportunities for robotics







AM presents fascinating opportunities for robotics







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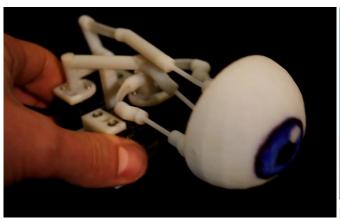
The Sci Fi vision...



[Intro to HBO's Westworld, https://www.youtube.com/watch?v=QRi3ULhyQq0] CRI

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The Sci Fi vision...



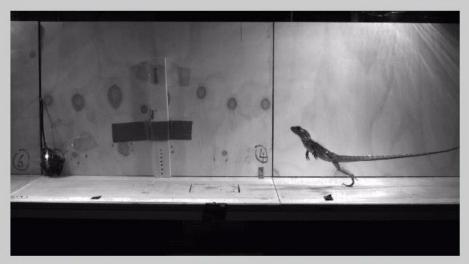


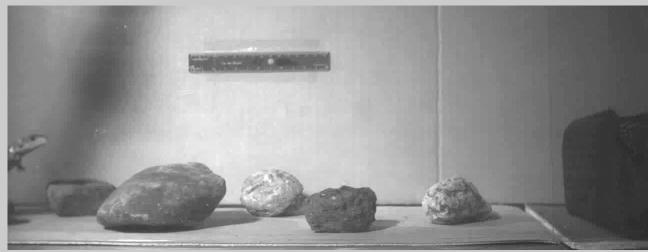


Exciting opportunities for robotics, but also for assistive technologies – prosthetics devices, wearables, etc...









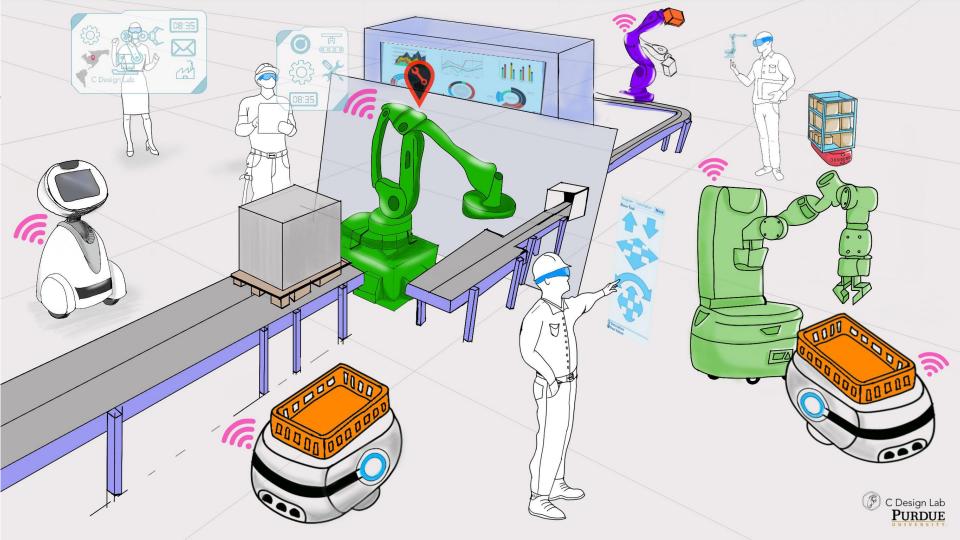


Industry 4.0

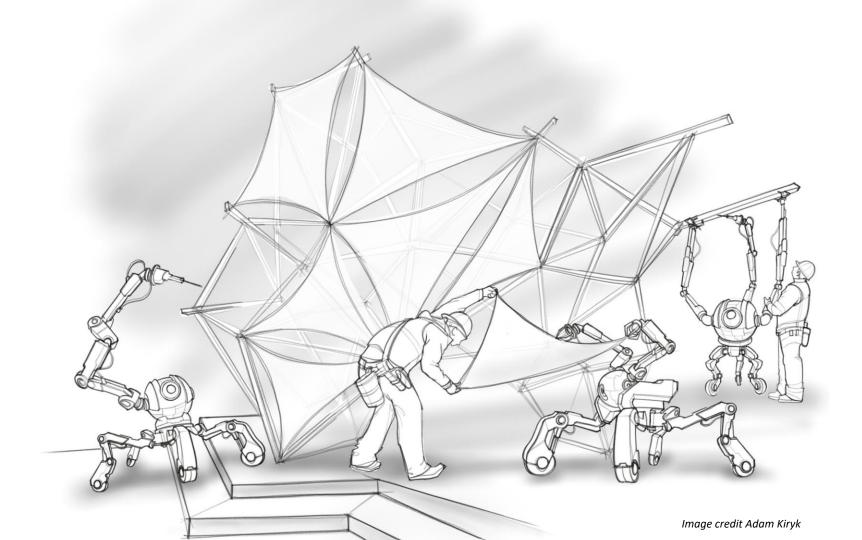




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Human-level skill and dexterity...

- **Grand Challenge**: robots must understand the physical implications of their actions
- once again, physics-based simulation models can come to the rescue...

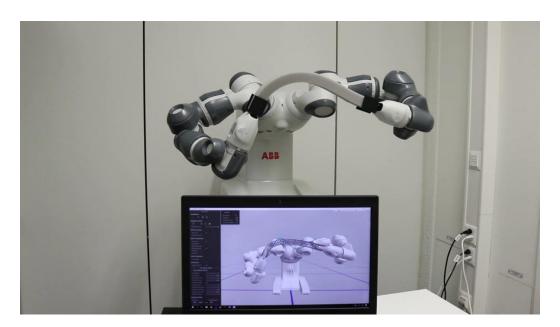






Human-level skill and dexterity...

Grand Challenge: robots must understand the physical implications of their actions



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On to: course schedule and logistics



